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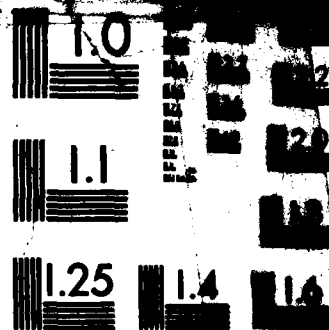
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ERRORS DUE TO COUNTING STATISTICS IN THE TRIAXIAL STRAIN
(STRESS) TENSOR DETERMINED BY DIFFRACTION

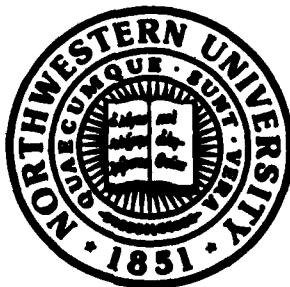
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ERRORS DUE TO COUNTING STATISTICS IN THE TRIAXIAL STRAIN (STRESS) TENSOR DETERMINED BY DIFFRACTION

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INTRODUCTION

→ Knowledge of the errors in a diffraction measurement of residual strains and stresses is useful information, not only in its own right, but also because it permits automation of a measurement to an operator specified precision.¹ There are three sources of these errors:

(1) Instrumental effects; primarily due to sample displacement, separation of the θ and 2θ axes of the diffractometer, and beam divergence. All three can be estimated², or minimized by employing parallel beam geometry.³

(2) Uncertainties in x-ray elastic constants; which can now be evaluated.⁴

and (3) Errors in the diffraction peak position related to counting statistics. (to #173)
Equations to evaluate this source have been developed in Ref. 1 for the case of a stress state for which all σ_{ij} ($i = 1, 2, 3$) = 0, with the direction "3" normal to the sample surface, see Fig. 1. This means that the stresses lie only in the surface, e.g., a biaxial stress state $\begin{vmatrix} \sigma_{11} & \sigma_{12} \\ \sigma_{12} & \sigma_{22} \end{vmatrix}$. There are, however,

numerous situations when the normal components are appreciable in an x-ray measurement^{5,6} and this is generally the case for neutron diffraction because with neutrons the beam can sample a sizeable volume, at a significant depth below the surface⁷. It

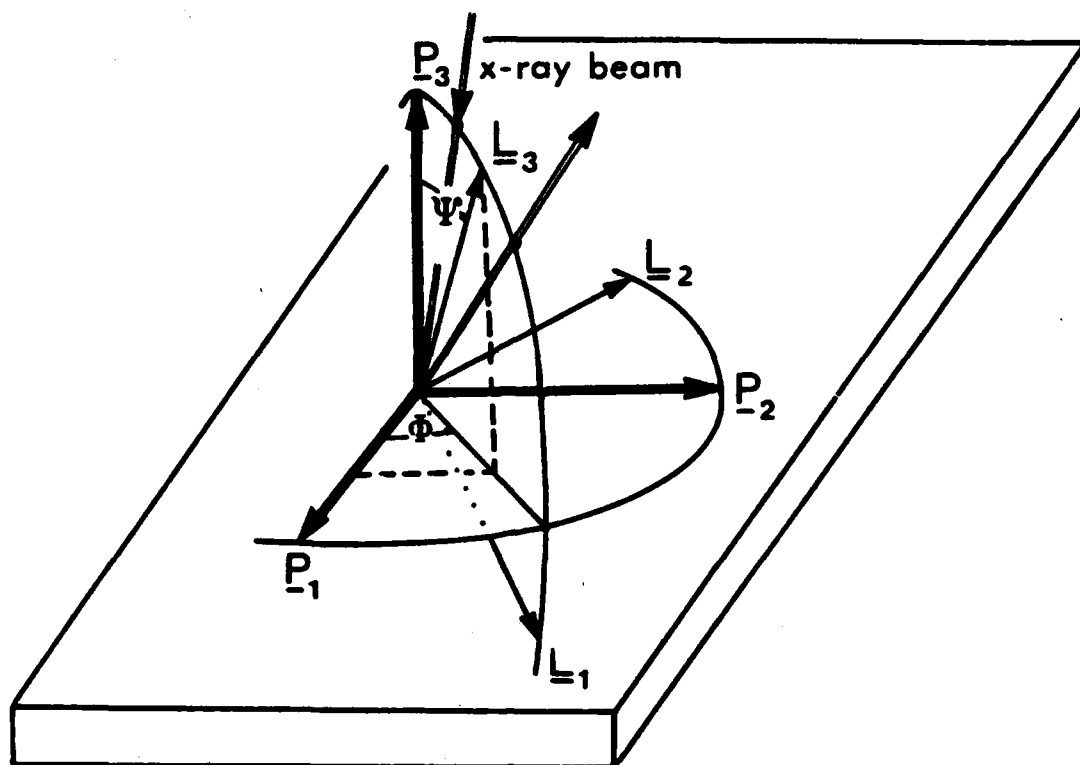


FIG. 1: The axial system. Strains are measured with diffraction by measuring the change in spacing of planes normal to the L_3 direction. (The axes P_1 define the specimen surface.)

TABLE I: STRESS TENSORS (AND STANDARD DEVIATIONS)
FOR SPECIMEN C3, REF. 5

DATA SET 1					
537.62	(161.94)	-24.03	(78.81)	-39.15	(4.58)
		550.04	(161.66)	2.31	(3.56)
				78.29	(130.57)
DATA SET 2					
520.60	(137.25)	-4.03	(66.60)	-34.17	(3.21)
		555.19	(137.03)	0.11	(2.69)
				82.20	(110.67)
DATA SET 3					
535.03	(158.28)	-20.13	(77.06)	-40.19	(5.72)
		555.98	(157.99)	-0.98	(4.56)
				86.66	(127.69)
DATA SET 4					
538.53	(146.23)	-30.63	(70.95)	-38.03	(3.83)
		565.37	(146.14)	0.76	(3.89)
				88.18	(117.92)
AVERAGE					
532.95	-19.69	-37.89			
	556.65	0.55			
		83.83			
REFERENCE 5					
	541	-20	-38		
		565	1		
			86		

* values given in MPa; $V(d_0)^{1/2} = 0.00016 \text{ \AA}$

is the purpose of this paper to derive equations to evaluate the counting statistical error for the entire three dimensional strain (or stress) tensor,

$$\begin{vmatrix} \sigma_{11} & \sigma_{12} & \sigma_{13} \\ \sigma_{12} & \sigma_{22} & \sigma_{23} \\ \sigma_{13} & \sigma_{23} & \sigma_{33} \end{vmatrix}.$$

BASIC EQUATIONS

We begin with the general equation for the strains (ϵ_{ij}) and how these affect the interplanar spacing "d". (Refer to Fig. 1 for the axial system.) The measurement is made in the θ direction, with a sample tilted ϕ from the normal position (which is with the surface normal bisecting incident and scattered beams). Primed quantities refer to strains in the L_1 co-ordinate system, unprimed terms are in the P_1 system.

$$\begin{aligned} \langle \epsilon'_{33} \rangle_{\theta\phi} &= (d_{\theta\phi} - d_0)/d_0 = [\langle \epsilon_{11} \rangle \cos^2 \theta + \langle \epsilon_{22} \rangle \sin^2 \theta + \langle \epsilon_{12} \rangle \sin 2\theta \\ &\quad - \langle \epsilon_{33} \rangle \sin^2 \phi + \langle \epsilon_{33} \rangle + [\langle \epsilon_{13} \rangle \cos \theta + \langle \epsilon_{23} \rangle \sin \theta] \sin 2\phi] \sin^2 \phi \end{aligned} \quad (1)$$

Note that the stress-free spacing, d_0 , is involved. While this term can be eliminated for a biaxial stress state, this is not possible for a general strain or stress tensor, and the reader may consult Ref. 8 for a discussion of problems associated with the measurement of this quantity. When ϵ_{12} , or ϵ_{13} , $\neq 0$, ϵ'_{33} is not linear with $\sin^2 \phi$ and has different curvature for $+\phi$ and $-\phi$. The carats imply that the strain values are averaged over the depth of penetration of the incident x-ray (neutron) beam and this is to be understood in what follows, as this additional notation is eliminated below.

Next, we define terms which involve measurements of $d_{\theta,\phi}$ at plus and minus ϕ tilts of the surface normal.⁵

$$\begin{aligned} a_1 &\equiv 1/2[\epsilon'_{\theta\phi+} + \epsilon'_{\theta\phi-}] = (d_{\theta\phi+} + d_{\theta\phi-})/2d_0 - 1 \\ &= \epsilon_{33} + [\epsilon_{11} \cos^2 \theta + \epsilon_{22} \sin^2 \theta + \epsilon_{12} \sin 2\theta - \epsilon_{33}] \sin^2 \phi \end{aligned} \quad (2a)$$

Clearly, a_1 , should be linear with $\sin^2 \phi$ and ϵ_{33} is the intercept, regardless of θ .

$$\begin{aligned} a_2 &\equiv 1/2[\epsilon'_{\theta\phi+} - \epsilon'_{\theta\phi-}] = (d_{\theta\phi+} - d_{\theta\phi-})/2d_0 \\ &= [\epsilon_{13} \cos \theta + \epsilon_{23} \sin \theta] \sin |2\phi|. \end{aligned} \quad (2b)$$

Therefore, a_2 is linear vs. $\sin|2\phi|$.

Let:

$$L_1 = da_1/d\sin^2\phi, \quad (3a)$$

$$L_2 = da_2/d\sin|2\phi| \quad (3b)$$

$$\text{Then, at: } \phi = 0^\circ, \quad L_1 = e_{11} - e_{33},$$

$$\phi = 90^\circ, \quad L_1 = e_{22} - e_{33},$$

$$\begin{aligned} \phi = 45^\circ, \quad L_1 &= 1/2(e_{11} + e_{22}) + e_{12} - e_{33}, \\ &= e_{12} + 1/2(e_{11} + e_{22}). \end{aligned} \quad (3c)$$

and similarly:

$$\text{at } \phi = 0^\circ: \quad L_2 = e_{13},$$

$$\text{at } \phi = 90^\circ: \quad L_2 = e_{23}. \quad (3d)$$

Knowledge of the strain tensor permits the calculation of the stress components (σ_{ij}) from:

$$\begin{aligned} \sigma_{ij} &= [1/2S_2(hkl)]^{-1} \{e_{ij} - \delta_{ij} \{S_1(hkl)/[3S_1(hkl) \\ &\quad + 1/2S_2(hkl)]\} \cdot [e_{11} + e_{22} + e_{33}]\}. \end{aligned} \quad (4)$$

Here, δ_{ij} is the Kronecker delta function and S_1 and $1/2S_2$ are the x-ray elastic constants which depend on the indices of the diffraction peak, hkl . (For an isotropic solid these values are $-v/E$ and $(1+v)/E$ respectively.)

VARIANCES DUE TO COUNTING STATISTICS

For a function $X = f(x_1, x_2, x_3 \dots)$, assuming the x_n are independent, the variance (V) is⁹:

$$V(X) = \left(\frac{dX}{dx_1}\right)^2 V(x_1) + \left(\frac{dX}{dx_2}\right)^2 V(x_2) + \left(\frac{dX}{dx_3}\right)^2 V(x_3) + \dots \quad (5)$$

For the straight line, $y = mx + b$, the slope and intercept is given by:

$$m = \frac{\sum_1 (x_1 - \bar{x})(y_1 - \bar{y})}{\sum_1 (x_1 - \bar{x})^2} \quad (6a)$$

$$b = (\sum y_1 - m \sum x_1)/N \quad (6b)$$

where N is the number of data points.

Employing Eq. (5):

$$V(m) = \left[\frac{\sum_1 (y_1 - \bar{y})}{\sum_1 (x_1 - \bar{x})^2} \right]^2 V(x) + \left[\frac{\sum_1 (x_1 - \bar{x})}{\sum_1 (x_1 - \bar{x})^2} \right]^2 V(y) \quad (6c)$$

Therefore:

$$V(b) = \frac{\sum_1 (x_1 - \bar{x})^2}{N} \cdot V(m) = \frac{\sum_1 (x_1 - \bar{x})^2}{N} \cdot \left\{ \frac{\sum_1 (y_1 - \bar{y})^2}{\sum_1 (x_1 - \bar{x})^2} V(x) + \left[\frac{\sum_1 (x_1 - \bar{x})}{\sum_1 (x_1 - \bar{x})^2} \right]^2 V(y) \right\} \quad (6d)$$

Therefore; in terms of a_1 vs. $\sin^2 \phi$:

$$V(a_1) = \left[\frac{\sum_1 (a_{11} - \bar{a}_1)}{\sum_1 (\sin^2 \phi_1 - \overline{\sin^2 \phi})} \right]^2 V(\sin^2 \phi) + \left[\frac{\sum_1 (\sin^2 \phi_1 - \overline{\sin^2 \phi})}{\sum_1 (\sin^2 \phi_1 - \overline{\sin^2 \phi})^2} \right]^2 V(a_1) \quad (7)$$

The variance in ϕ is negligible, so the first term can be ignored.

Also, from Eq. (2a):

$$V(a_1) = \left[\frac{da_1}{d(d_{\phi\phi+})} \right]^2 V(d_{\phi\phi+}) + \left[\frac{da_1}{d(d_{\phi\phi-})} \right]^2 V(d_{\phi\phi-}) + \left[\frac{da_1}{d(d_0)} \right]^2 V(d_0) \quad (8)$$

Writing Bragg's law in the form $d = \frac{\lambda}{2\sin\theta}$, adopting the convention that θ^+ , θ^- are the θ values (in degrees) for the peaks at $+\phi$, $-\phi$ respectively, and employing Eq. (5):

$$V(d_{\phi\phi+}) = (\pi/180)^2 (\lambda \cos \theta^+ / 2 \sin^2 \theta^+)^2 V(2\theta^+) / 2 \quad (9)$$

and similarly for $V(d_{\phi\phi-})$. Recalling Eq. (2a):

$$\left[\frac{da_1}{d(d_{\phi\phi+})} \right]^2 = \left[\frac{da_1}{d(d_{\phi\phi-})} \right]^2 = \frac{1}{4d_0^2}, \quad (10a)$$

$$-\frac{da_1}{d(d_0)} = \frac{[d_{\phi\phi+} + d_{\phi\phi-}]^2}{4d_0^4} = d_+^2/4d_0^4. \quad (10b)$$

Thus, we may rewrite Eq. (7):

$$V(\ell_1) = \left[\frac{\sum_1 (\sin^2 \phi_1 - \overline{\sin^2 \phi})}{\sum_1 (\sin^2 \phi_1 - \overline{\sin^2 \phi})^2} \right]^2 \frac{1}{4d_0^2} \left\{ \left(\frac{\pi}{180} \right)^2 \frac{\lambda^2}{8} \left[\left(\frac{\cos \theta^+}{\sin^2 \theta^+} \right)^2 v_1(2\theta^+) \right. \right. \\ \left. \left. + \left(\frac{\cos \theta^-}{\sin^2 \theta^-} \right)^2 v_1(2\theta^-) \right] + (d_+^2/d_0^2) V(d_0) \right\} \quad (11)$$

In a similar manner for a_2 vs. $\sin|2\phi|$, where $a_2 \equiv (d_{\phi\phi-} - d_{\phi\phi+})/2d_0 = d_-/2d_0$:

$$V(\ell_2) = \left[\frac{\sum_1 \sin|2\phi_1| - \overline{\sin|2\phi|}}{\sum_1 (\sin|2\phi_1| - \overline{\sin|2\phi|})^2} \right]^2 \frac{1}{4d_0^2} \left\{ \left(\frac{\pi}{180} \right)^2 \left(\frac{\lambda^2}{8} \right) \left[\left(\frac{\cos \theta^+}{\sin^2 \theta^+} \right)^2 v_1(2\theta^+) \right. \right. \\ \left. \left. + \left(\frac{\cos \theta^-}{\sin^2 \theta^-} \right)^2 v_1(2\theta^-) \right] + (d_-^2/d_0^2) V(d_0) \right\} \quad (12)$$

We now propagate these values into the strain and stress tensors.

THE STRAIN TENSOR

Abbreviating the intercept of a_1 vs. $\sin^2 \phi$ as I , then at any ϕ :

$$\epsilon_{33} = I \text{ (of } a_1 \text{ vs. } \sin^2 \phi), \quad (13a)$$

$$V(\epsilon_{33}) = V(\ell_1) + V(I) \quad (13b)$$

$$V(I) = \frac{\sum (\sin^2 \phi_1 - \overline{\sin^2 \phi})^2}{N} \cdot \left[\frac{\sum (\sin^2 \phi_1 - \overline{\sin^2 \phi})}{\sum (\sin^2 \phi_1 - \overline{\sin^2 \phi})^2} \right]^2 V(a_{11}) \\ = \frac{1}{N} \frac{[\sum (\sin^2 \phi_1 - \overline{\sin^2 \phi})]^2}{\sum (\sin^2 \phi_1 - \overline{\sin^2 \phi})^2} V(a_{11}) \quad (13c)$$

Now, from Eqs. (3c), at $\phi = 0^\circ$:

$$\epsilon_{\ell_1} = \epsilon_{11} - \epsilon_{33} = \epsilon_{11} - I, \quad (14)$$

$$V(\epsilon_{\ell_1}) = 2V(\epsilon_{11}) + V(I).$$

Similarly, for $\phi = 90^\circ$:

$$\epsilon_{22} = \epsilon_0 \epsilon_1 + I,$$

$$V(\epsilon_{22}) = V(\epsilon_0 \epsilon_1) + V(\epsilon_0 \epsilon_1) + V(I), \quad (15)$$

and for $\theta = 45^\circ$:

$$\epsilon_{12} = \epsilon_0 \epsilon_1 + \epsilon_{33} - 0.5 (\epsilon_{11} + \epsilon_{22})$$

$$+ \epsilon_0 \epsilon_1 - 0.5 (\epsilon_0 \epsilon_1 + \epsilon_0 \epsilon_1),$$

$$V(\epsilon_{12}) = V(\epsilon_0 \epsilon_1) + 0.25 [V(\epsilon_0 \epsilon_1) + V(\epsilon_0 \epsilon_1)]. \quad (16)$$

From Eqs. (3d):

$$V(\epsilon_{12}) = V(\epsilon_0 \epsilon_2), \quad (17)$$

$$V(\epsilon_{23}) = V(\epsilon_0 \epsilon_2). \quad (18)$$

THE STRESS TENSOR

We define $Q = S_1 / (3S_1 + 1/2S_2)$ (which is $[-\nu/1-2\nu]$ for an isotropic solid). Then Eq. (4) may be written, for the diagonal stress components, as:

$$\sigma_{ij} = (1/2S_2)^{-1} [(1-Q)\epsilon_{ii} - Q\epsilon_{kk} - Q\epsilon_{jj}]. \quad (19)$$

Here $i = 1, 2, 3$; $j = 2, 3, 1$; $k = 3, 1, 2$.

From Eq. (19):

$$V(\sigma_{ii})^{\frac{1}{2}} = (1/2S_2)^{-1} \{ (1-Q)^2 V(\epsilon_{ii}) + Q^2 [V(\epsilon_{kk}) + V(\epsilon_{jj})] \}^{\frac{1}{2}}. \quad (20)$$

Therefore, with Eqs. (13-15):

$$V(\sigma_{11})^{\frac{1}{2}} = (1/2S_2)^{-1} \{ (2-4Q + 4Q^2)V(\epsilon_0 \epsilon_1) + Q^2 V(\epsilon_0 \epsilon_1) + (1-2Q + 3Q^2)V(I) \}^{\frac{1}{2}}, \quad (21)$$

$$V(\sigma_{22})^{\frac{1}{2}} = (1/2S_2)^{-1} \{ (1-2Q + 4Q^2)V(\epsilon_0 \epsilon_1) + (1-2Q + Q^2)V(\epsilon_0 \epsilon_1) + (1-2Q + 3Q^2)V(I) \}^{\frac{1}{2}}, \quad (22)$$

$$V(\sigma_{33})^{\frac{1}{2}} = (1/2S_2)^{-1} \{ (1-2Q + 4Q^2)V(\epsilon_0 \epsilon_1) + Q^2 V(\epsilon_0 \epsilon_1) + (1-2Q + 3Q^2)V(I) \}^{\frac{1}{2}} \quad (23)$$

$$V(\alpha_2)^{\frac{1}{2}} = (1/2S_2)^{-1} [V(\epsilon_1) + 0.25 [V(\epsilon_1) + V(\epsilon_1)]]^{\frac{1}{2}}, \quad (24)$$

$$V(\alpha_1)^{\frac{1}{2}} = (1/2S_2)^{-1} V(\epsilon_2)^{\frac{1}{2}}, \quad (25)$$

$$V(\alpha_2) = (1-2S_2)^{-1} V(\epsilon_2). \quad (26)$$

EXAMPLES

To illustrate the typical magnitudes of the errors due to counting statistics, we employed data from Ref. 5, for a ground steel specimen, that is we used the peak positions and the variances in these positions with Eq. (9). [Formulae to calculate this variance for the parabolic fit employed in Ref. 5 are given in Ref. 1; for other types of fits the appropriate equation may be substituted.] The resultant errors are given in Tables I-III. For the first two tables it was assumed that the error in d_{ϕ} was the actual measured value. If there is no preferred orientation, the intensity of the peak changes little with the ϕ -tilt. In this case, Tables I and II show the effect of the uncertainty in d_0 ; reducing this error all the stress components by the same proportion, except α_1 , α_2 , which remain relatively unaffected, because the role of the error in d_0 is damped by $(d_0)^2$ in Eq. (12).

If there is preferred orientation, the peak intensity can vary greatly with ϕ and there will be large variances contributing to $V(\epsilon_1)$ from weak peaks. This was minimized in the following way. The average variance, σ_1 , in the 2θ peak position for $+\phi$ and $-\phi$ was obtained and the weighting factor c_1 was formed:

$$c_1 = (1/\sigma_1^2) / \sum_i (1/\sigma_i^2) \quad (27)$$

The Eqs. 11 and 12 were then altered to multiply $V_1(2\theta^+)$, $V_1(2\theta^-)$ terms by this weighting for Table III. There is only a small difference (between Tables II and III) because of the lack of texture in the specimen; the peak intensity changed only by about 8 pct with ϕ . With more severe preferred orientation the effect will be larger.

CONCLUDING REMARKS

There are now adequate equations for calculating errors in stress

TABLE II: STRESS TENSOR AND STANDARD DEVIATIONS WHEN
 $V(d_0)^{\frac{1}{2}} = 0.00004 \text{ \AA}^*$

		DATA SET 1			
539.74	(48.24)	-24.03	(24.50)	-39.15	(4.58)
		552.16	(47.26)	2.30	(3.56)
				80.41	(38.96)
		DATA SET 2			
520.60	(40.52)	-4.03	(19.95)	-34.17	(3.21)
		555.19	(39.73)	0.11	(2.69)
				82.20	(32.75)
		DATA SET 3			
535.03	(47.81)	-20.14	(24.35)	-40.19	(5.72)
		555.98	(46.81)	-0.98	(4.56)
				86.66	(38.84)
		DATA SET 4			
538.53	(42.84)	-30.63	(21.10)	-38.03	(3.83)
		565.37	(42.51)	0.76	(3.89)
				88.18	(34.67)

*values given in MPa

TABLE III: WEIGHTED STRESS TENSOR AND STANDARD DEVIATIONS*

		DATA SET 1			
536.24	(48.56)	-24.62	(24.56)	-38.33	(4.59)
		554.65	(47.60)	2.90	(3.65)
				80.68	(39.22)
		DATA SET 2			
520.29	(41.84)	-6.04	(20.11)	-34.82	(3.55)
		560.22	(40.60)	1.56	(2.73)
				85.29	(33.76)
		DATA SET 3			
532.56	(48.15)	-7.90	(24.93)	-39.66	(5.81)
		549.83	(47.16)	-2.81	(4.57)
				82.21	(39.16)
		DATA SET 4			
539.23	(42.88)	-31.22	(21.23)	-38.28	(3.85)
		565.17	(42.65)	-0.59	(3.94)
				88.98	(34.68)

* $V(d_0)^{\frac{1}{2}} = 0.00004 \text{ \AA}$; values given in MPa

measurements due to instrumental effects, counting statistics and in the x-ray elastic constants. We would like to conclude this paper with a plea to the community making stress measurements via diffraction to regularly report these errors with their data. It is all too common for investigators to repeat a measurement (of stress or an elastic constant) once and to use the difference as an error estimate. Another practice is to dust a stress-free powder on the specimen surface and to use a (single) measurement of the stresses measured with this powder as an error estimate. Finally, some report an error in a slope vs. $\sin^2\psi$ obtained by least-squares, but ignore the uncertainty in each point in this plot in estimating errors. None of these procedures is particularly satisfying in a statistical sense. Of course, if time permits, the average of, say, ten repetitions of a measurement is the best of all error estimates. If this cannot be done, error estimates from the available equations are far more satisfactory than the currently all - too common procedures.

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The errors are derived for the diffraction measurement of the three dimensional stress and strain tensor due to counting statistics. *7*

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